Leesburg Library - Map Plan

Captured: Nov 06, 2019, Processed: Nov 07, 2019



Map Details Summary (i)

Project Name	Leesburg Library - Map Plan
Photogrammetry Engine	DroneDeploy Proprietary
Date Of Capture	Nov 06, 2019
Date Processed	Nov 07, 2019
Processing Mode	Structures (3D)
GSD Orthomosaic (GSD DEM)	0.38in/px (DEM 1.52in/px)
Area Bounds (Coverage)	144112.25ft ² (118%)
Image Sensors	Hasselblad - L1D-20c

Quality & Accuracy Summary (i)

lmage Quality	High texture images
Median Shutter Speed	1/120
Processing Mode	Structures (3D) - Designed to produce high resolution 3D maps containing overhangs, for example of buildings, pipework & conveyors. Images captured should include oblique imagery. Map processing will typically take longer than terrain mode. Should not be used for mapping crops or large flat or smooth topographic scenes.
Images Uploaded (Aligned %)	351 (100.0%)
Camera Optimization	Principal point varied from reference value by 8.36%.

Preview (i)





Dataset Quality Review (i)

Orthomosaic Coverage (i)



• Unaligned ×

ROI

Insufficient coverage, expect large holes in the map, and low accuracy.

Marginal coverage, expect distortion or holes on buildings or sharp edges, and lower accuracy measurements.

Good coverage, expect a high quality reconstruction

Sensor(s) Used	Hasselblad - L1D-20c
Image Count (by sensor)	351
Image Resolution	5472x3078 (~17MP)
Orthomosaic coverage (% of area of interest)	118.22
Average Orthomosaic Image Density within Structured Area	40 images/pixel
Median Shutter Speed	1/120

Structure from Motion (i)

Aligned Cameras	100% 350/351
RMSE of Camera GPS Location	X 1.66ft Y 1.73ft Z 5.98ft RMSE 3.72ft

Camera Calibration (i)



Densification and Meshing $(\!i\!)$

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Processing Mode Quality	High
Nadir Images	0%
Oblique images	95%
Horizontal images	5%
Mesh Triangles	809574

Digital Elevation Model (\hat{i})

Mode	Generated from Mesh	
DEM GSD	DEM 1.52in/px	
Relative/Absolute	Absolute Altitude	





This map and report was produced with proprietary cloud photogrammetry software from DroneDeploy. Provide feedback to improve this report